Troubleshooting & Diagnostic Procedures

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TROUBLESHOOTING & DIAGNOSTIC PROCEDURE

The specific EML control system you happen to be troubleshooting/diagnosing dictates what method of diagnostic procedure you must follow.

Before the DIS was available, the Diagnostic Manuals provided information for diagnostic procedure. There are Diagnostic Manuals for the E32/34 and E31 vehicles. These manuals are still an excellent source of information for pre DIS systems.

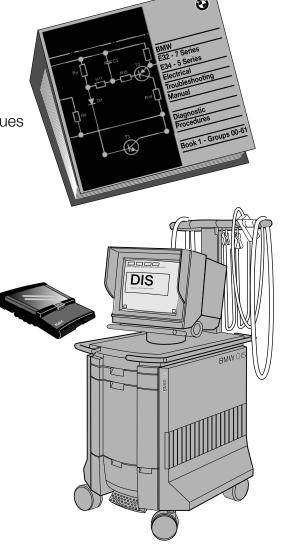
The Diagnostic Manuals provide:

- System Functional Descriptions
- Info on the control module's diagnostic system.
- Abbreviations pertaining to system
- Control Module Pin assignments
- Troubleshooting test procedures with nominal values
- Defect/Fault Code explanations
- Component testing information
- Technical Data

With the introduction of the DIS all of the Diagnostic Manual information was incorporated into the DIS software for E-38 and E-46. Data communication with a specific control module provides an upto-date system specific interface. The DIS provides Fault Symptom troubleshooting procedures with access to Fault codes, Status Requests, Component Activation, Special Service functions, etc.

This section provides information regarding how the control modules communicate diagnostic information and/or fault recognition to the DIS and with each other via CAN communication.

Additionally, Control Module Variant Encoding or Control Module programming is another topic that must be considered when diagnosing a system. If a control module has been coded or programmed incorrectly, it could possibly induce driveability complaints and or incorrect system function.



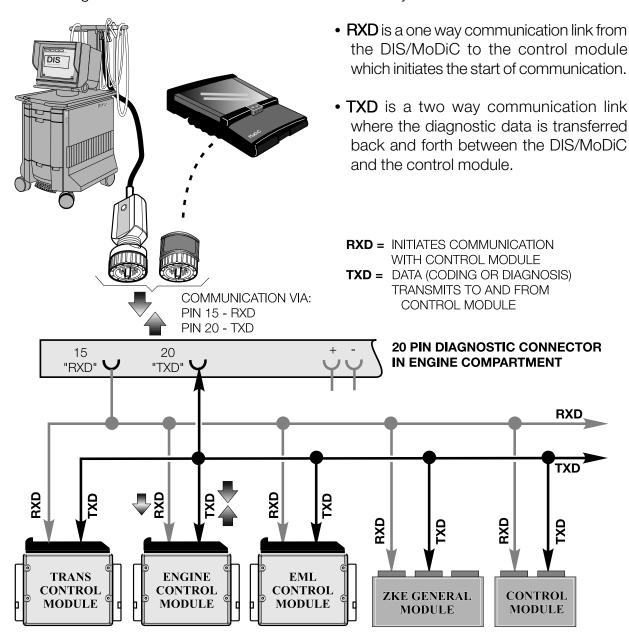
Finally, this section provides examples of using the Diagnostic Manual "Paper" information method in conjunction with the DIS and a system using the "DIS" alone.

DIAGNOSTIC COMMUNICATION

DIS/MoDiC to control module communication is dependent on the integrity of the Diagnostic Link (D-Bus). The diagnostic link is a wire circuit in the vehicle that connects to all control modules designed to communicate with the DIS tester. The connection point for the DIS with the diagnostic link in the vehicle is at the 20 pin diagnostic connector in the engine compartment.

The diagnostic link has evolved through the model years as follows:

RXD/TXD: The wires in the 20 pin connector are identified as RXD (pin 15) and TXD (pin 20). This configuration is used with all M1.x and M3.x DME systems.



TXD II: With the introduction of OBD II, the diagnostic link changed to meet the needs of the OBD II Data Link Connector (DLC). The DLC is located in the passenger compartment and provides a connection for an aftermarket scantool for powertrain systems only. Scantool communication with these control modules is only possible when the 20 pin diagnostic connector cap is installed. A circuit bridge in the cap completes the DLC circuit.

The original RXD/TXD link is still in the vehicle for non powertrain systems. But, (control module dependent) RXD may not be used at all since later control modules communicate with the D2 protocol (different language) which only requires TXD (single wire communication).

TXD II (pin 17) was added to the 20 pin diagnostic connector to provide a separate connection to Drivetrain control modules (DME, AGS, EML) for OBD II compliance. The separate connection is for security reasons. The DIS/MoDiC share the same TXD II wire though the scantool and DIS/MoDiC communicate with different "languages".

DIS/MoDiC

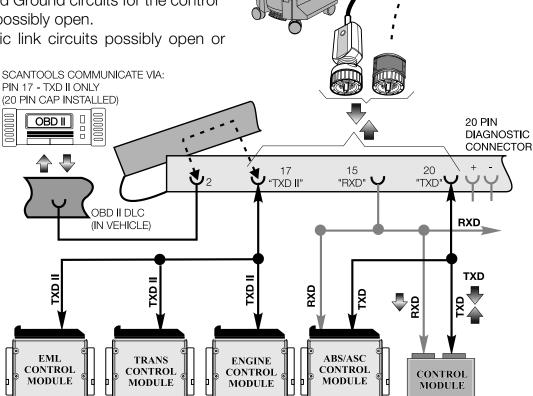
PIN 20 - TXD

COMMUNICATION VIA: PIN 15 - RXD

- Scantool "speaks" ISO 9141 protocol.
- DIS/MoDiC "speak" D2 protocol.

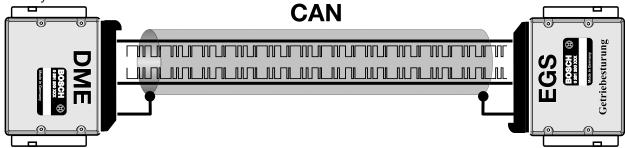
If problems are encountered trying to establish communication, consider the following:

- Battery voltage too low (connect a battery charger prior to communication).
- Power and Ground circuits for the control module possibly open.
- Diagnostic link circuits possibly open or shorted.



CAN BUS TOPOLOGY

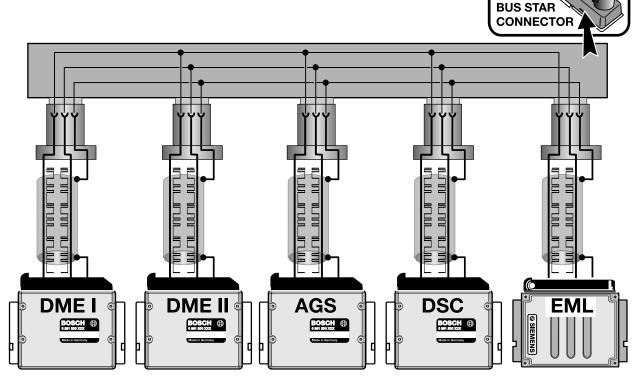
Introduced with the 1993 740i/iL, the Controller Area Network (CAN) provides a fast communication link between the Engine and Transmission Control Modules serving as both an input and output multiple signal bus. The CAN consists of two wires (CAN High and CAN Low) with a ground shield. In it's the early configuration, the CAN bus is a simple end user bus system.



With the introduction of the 1995 750iL, the CAN bus was expanded to include both engine control modules, transmission control module, EML IIIs control module and the DSC II control module.

A "star coupler connector" was used to link the individual CAN bus leads from the modules into one common connector strip.

The 740i/iL models do not use the star connector. The single DME, AGS and ASC control modules are linked at a splice point in the wiring harness.

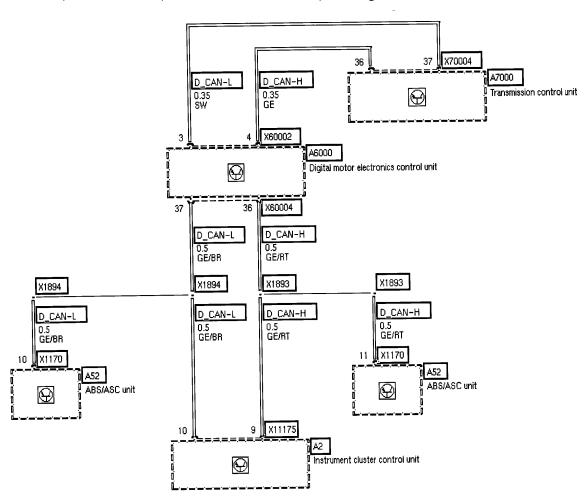


CAN

The 1998 model year brought forth the next generation of CAN Bus communicators. The Instrument Cluster and Steering angle sensor of the DSC III system were also linked to the CAN bus to expand the available signalling capabilities.

The Star connector continues to be used for the 750iL but wiring layout (topology) was changed to improve communication integrity in the event of a break or short in another section of the CAN bus. This was accomplished by using the DME control modules as gateways for the EML and AGS control modules.

Additionally, twisted pair wiring is used for the Instrument Cluster and Steering Angle Sensor which provides EMI protection without a separate ground shield.



The CAN bus of the 1998 740i/iL and 540i has also changed. The entire CAN bus is twisted pair wiring. The EGS is linked to the DME by a dedicated twisted pair CAN bus with a common twisted pair to all other control modules.

The CAN bus must be considered when diagnosing an engine control system. Faults may manifest due to a breakdown in a segment of the CAN bus with another control module causing a fault to display in the engine control module only due to lack of CAN bus data. When diagnosing a specific system, always refer to the ETM for up-to-date configurations.

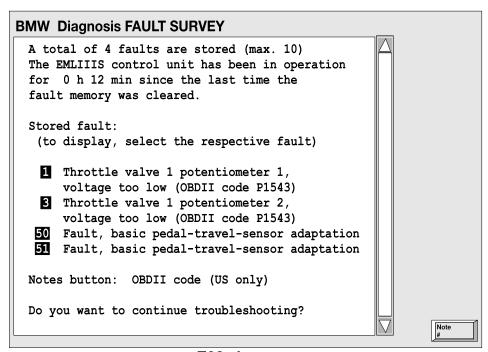
CONTROL MODULE VARIANT ENCODING AND PROGRAMMING

The possibility exists that an incorrectly coded or programmed control module will cause system faults and or driveability complaints with no faults found.

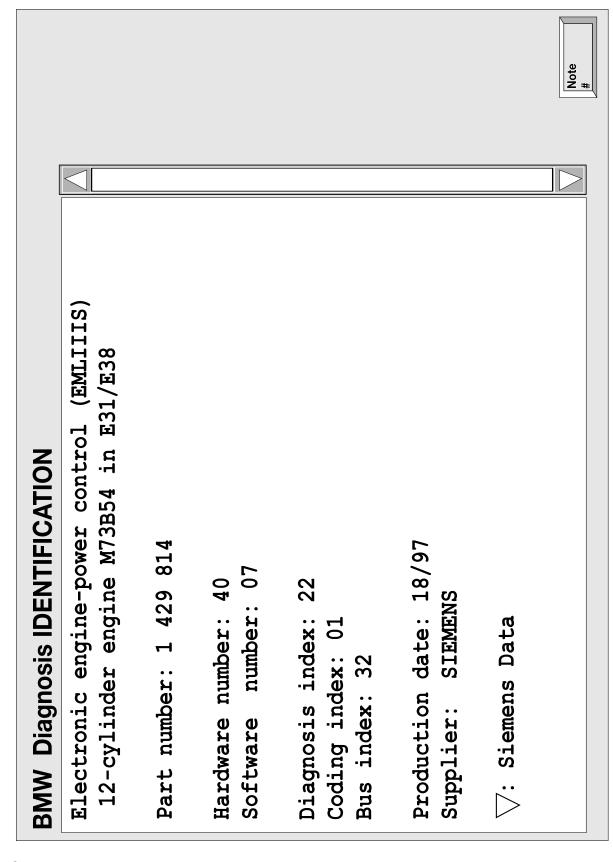
This possibility should always be considered (prior to assuming a control module defective) and is easily checked by connecting the DIS/MoDIC and displaying the ID page.

Because of the interaction between the various control units of the Driving Management System, and the various specific model applications, the EML Control Unit is programmed and "coded" for the proper model application (E31, E32/34, E38). Coding is written into the software package of the Control Unit, and identified by the Software Code number. It is also used to identify any updates in the programming.

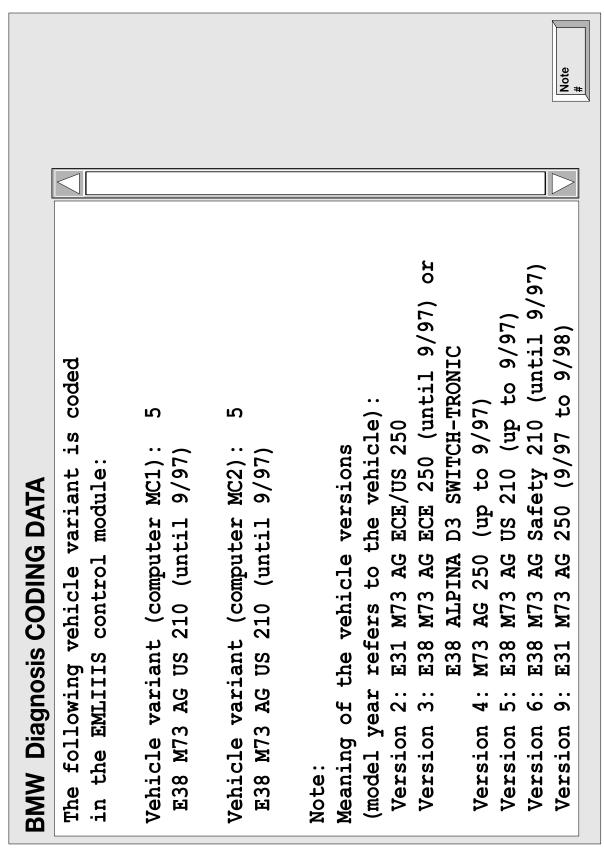
The proper application of the EML Control Unit can be verified by the:

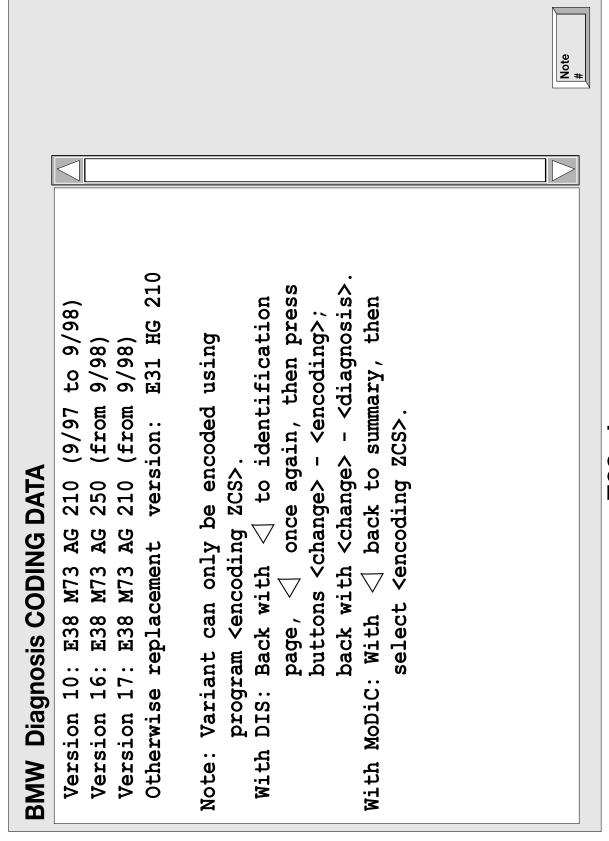


E38 shown



BMW Diagnosis IDENTIFICATION	
Electronic engine-power control (EMLIIIS)	
Siemens Data:	
Modification index: a0 Production number: 31672471	
	Note #





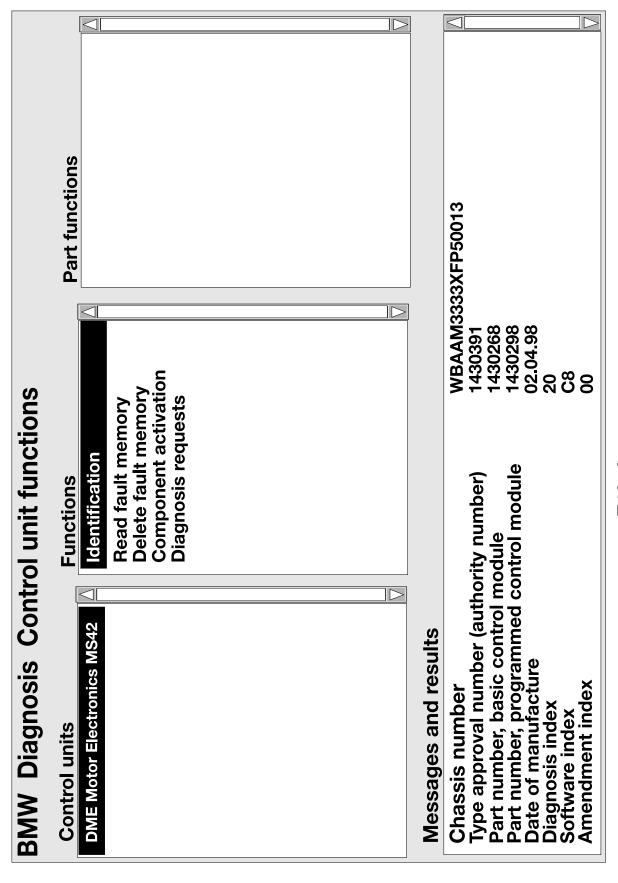
PROGRAMMABLE CONTROL MODULES: SIEMENS MS42.0

- The ID page provides the part numbers of the control modules. Compare these numbers to what should be in the vehicle by referring to SI 13 02 90. Also, perform a determination process with the DIS/MoDIC for correct part numbers.
- Look into the vehicle history file for possible service action that have been performed on the vehicle.
- If the programming has been performed on the control module recently, consider reprogramming it.

Refer to *Understanding Control Module Coding and Programming* for complete information, procedures and troubleshooting information.

This publication was originally mailed to every Tracs registered Retailer Technician in 1995. This material is also part of BMWs Technical Introductory Course; Technical Systems (ST 050).





E46 shown

Electronic Throttle Control (EML, 12-Cylinder)

Notes on BMW DIAGNOSE-SYSTEM

Defect Code Memory

trolled by the DML control unit, but not stored as a defect code in the case The component functions and signals listed below are processed or conof defect:

- LL-signal (sends the "idle" information to the DME)
- VL-signal (sends the "full load" information to the DME)
- A/C switch
- A/C compressor clutch (lock sensor)
- Range selector switch ("P" or "N" position in automatic transmission)
 - Clutch switch (manual transmission)
 - Brake light switch
 - External safety path

The external safety path cannot be read out in the status lists of the BMW DIAGNOSTIC SYSTEM.

Defect Code Priority

fect code memory is full, a new defect code with higher priority displaces The EML control unit stores a maximum of 5 defect codes. When the dea lower priority defect code already stored (see ◆D◆ # Notes)

Status Monitoring

Since all inputs and outputs and their plausibilities are not covered by the defect code memory of the EML control unit, the status monitoring functions must be used to facilitate troubleshooting.

not necessarily agree exactly. The EML control unit stores a defect code if the deviation between the nominal value and the actual value is outside The nominal values and actual values indicated in the status lists need the permissible range.

missible range has been exceeded and the EML control unit has detected For the permissible ranges, refer to the functional description or the troubleshooting description in the BMW DIAGNOSTIC SYSTEM. If the perhis as a defect, the component and its line connection can be checked without complex measurements with the aid of the actual value display.

BMW

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	Throttle reduction	Throttle increase	Manual transmission	Engine intervention	Pedal position sensor	Potentiometer	Engine speed signal (once per ignition)	Engine speed signal (three times per crankshaft revolu-	tion)	Engine temperature sensor	Injection signal	Idle signa	Full load signal	Torque converter clutch	Ignition fade-out
	DKR	DKE	쭛	ME	PWG	Poti	ይ	표		TMOT	æ	Ⅎ	۲	×	ZAB
Abbreviations	Anti-lock brake system	Automatic stability control	Digital engine electronics		Electronic throttle control	Rengine drag torque control	Output	Input	EML throttle						
Abb	ABS	ASC	DME	EGS	EM.	MSR	∢	ш	Š	<u> </u>	5				

Pin Assignments

Pin Assignments at the EML 12-cyl. Control Unit Connector X6004

	v				2H00										
	Measurement notes				♦ M ♦ 14 approx. 100Hz						♦M ♦ 14				
	Test display	None			Defect code is stored	NO	OFF	NO	OFF	Winkel	None	None		None	None
	Type of signal	approx. 5 V			Square-wave signal	approx.0 V	uedo	approx. 0 V	oben	approx. 0,4 V to 4 V	Square-wave signal	approx. 5 V		approx. 5 V	approx. 5 V
	Connection	PWG switch	Component ground PWG		ASC control unit	DME control unit	16. cylinder	DME control unit	16. cylinder	PWG potentiometer	Instrument cluster	PWG potentiometer	Component ground DK – 712. cylinder	DK potentiometer DK 712. cylinder	DK potentiometer DK 16. cylinder
	Type Description/Function	5V (not short -circuit-proof)	Ground (electronic ground)	Not used	DK angle reduction (DKR)	Full load signal		Idle signal		PWG setting	Road speed signal	5V (not short-circuit-proof)	Ground (electronic ground)	5V (nicht Kurzschlußfest)	5V (nicht Kurzschlußfest)
ı	Type	A	¥		ш	∢		4		ш	Е	∢	∢	∢	∢
į	Pin	-	2	က	4	က		9		7	8	6	10	Ŧ.	12

BMW 8

Electronic Throttle Control (EML, 12-Cylinder)

1270.1A-15 -

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Electronic Throttle Control (EML, 12-Cylinder)

rpe Description Diagnosis	Type Description/Function	Connection Diagnostic socket RxD	Type of signal	Test display	Measurement notes
	Ground (Output ground)	Output ground DK 16. cylinder			
A EML w	EML warning lamp	Instrument cluster	approx. 0 V	NO	*) With ignition switched
E Voltage 9 memory	Voltage supply for defect code memory		approx. 12 V	None	Jo
A Drive	Drive throttle (DK) actuator	DK actuator DK - 712. cylinder	Square-wave signal	Defect code is stored	
A Drive	Drive throttle (DK) actuator	DK actuator DK 16. cylinder	Square-wave signal	Defect code is stored	
E Voltaç	Voltage supply plus	DME main relay 16. cylinder	On-board volt- age	None	
E Ground	þ	Ground point			
A Kick-	Kick-down signal	EGS control unit	approx. 0 V	NO	
			approx. 12 V	OFF	
Not used	pes				
E DK a	DK angle increase (DKE)	ASC control unit	Square-wave signal	Defect code is stored	♦ M ♦ 14 approx. 100Hz
A Dross	Drosselklappensignal (DKV)	ASC / EGS	Square-wave signal	Defect code is stored	♦ M ♦ 14 approx. 100Hz
Not used	pes				
A 5 V (r	5 V (not short-circuit-proof)	DK – 16. cylinder (not used)	approx. 5 V		
A Grour	Ground (electronic ground)	Component ground DK 16. cylinder			
i					

© BMW Electronic Throttle Control (EML, 1	(EML, 12-Cylinder)	
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ω							04/90
Pin	Type	Pin Type Description/Function	Connection	Type of signal	Test display	Measurement notes	
53	m	E Brake light switch	Brake light switch	approx. 12 V	NO		
				oben	OFF		
24		Not used	The state of the s				
55	E/A	E/A Diagnosis	Diagnostic socket TxD				
Adap	Adapters	Connector No.	Description	Adapternumber	umber		
Confr	Control unit	X 6004	55-pole 55-pole 55-pole	Connection lead, Connection lead, Universal adapter	on lead, periphery on lead, control unit adapter	Connection lead, periphery HWB 81 12 9 428 907 Connection lead, control unit HWB 81 12 9 428 908 Universal adapter HWB 81 12 9 425 091	1270.1A
E E E	EML safety path	ath	Safety path testing	EML adapter	oter	Cartool 12 7 010	-18

Troubleshooting

Electronic Throttle Control (EML, 12-Cylinder)

Notes

Relevant safety codes and accident prevention regulations must be observed when carrying out all tests and work on the engine electronic system. Do not touch an EML throttle valve when it is in operation.

|mportant!

Wherever possible, the battery and the instrument cluster should not be disconnected otherwise all defect codes and teach—in values stored in the EML control unit will be deleted (see $\bullet D \bullet \#$ Notes).

Disconnect control unit from the wire harness \underline{only} when the ignition is switched off

Attention! The stage outputs of the EML control unit for the throttle (DK) actuators are not short-circuit-proof. In the same way, the 5 V component supply voltage coming from the EML control unit is not absolutely short-circuit-proof.

Organisation of the Defect Code Pages on the Display Screen

- Defect location: The defect can be in the vicinity of the component, the
 associated wires or in the control unit. The number before the defect code
 indicates the priority of the defect code (◆D◆ # Notes).
 - Type of defect: Range transgression or illogical (wrong sequence) functions are indicated.
- Detected at: Additional defect information on the operating statuses during defect detection (compare values with substitute values). This information can provide an indication relating to plausibility (correct sequence), shorts, breaks and range transgressions.

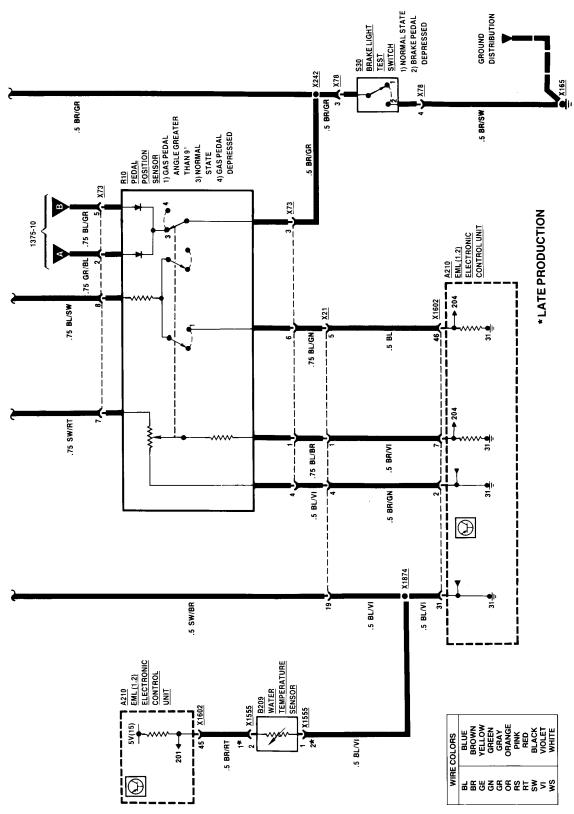
EML Warning Lamp

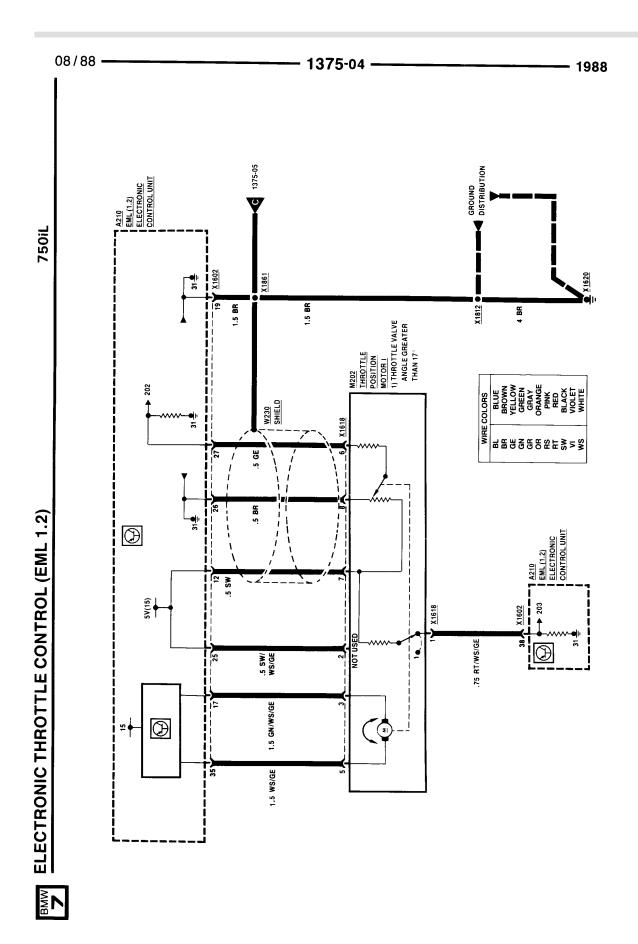
After switching on the ignition, EML control unit checks its vital components (safety check) and causes the EML warning lamp to light for approx. 2 seconds. The EML reduces the output if the EML warning lamp cannot be set due to a defect in the lamps or associated wires. The warning lamp continues to light if one of the defects 8 to 22 occurs after the safety check (◆D◆ # Notes).

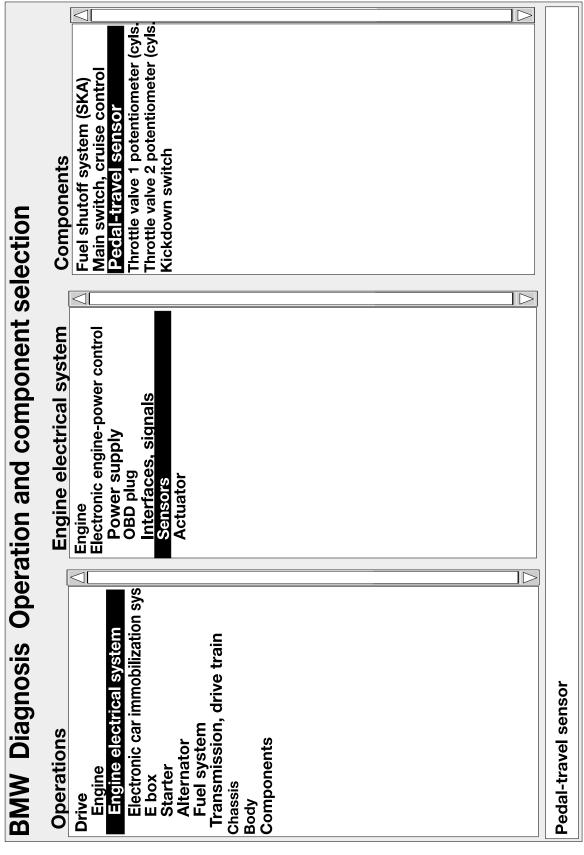
Defect Code Table

♦D♦ Defect code memory – stored defect codes

One or several defect codes stored → troubleshooting in accordance with BMW DIAGNOSTIC SYSTEM.







E46 shown

E38 shown

BMW Diagnosis FAULT SYMPTOMS

- 3 Engine dies while driving or cannot be started
- 4 Engine suffering from lack of power or poor throttle response
- poor throttle response

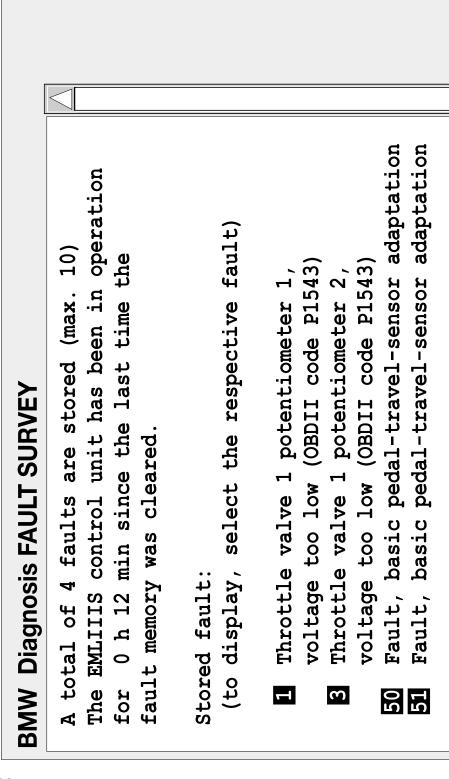
 Cruise-control system operation faulty
 - or not possible or not possible Engine only runs at idle speed and
- does not respond to throttle

 Fingine running with top-speed regulation
- 8 Idle-speed control not perfect
- (Idle-actuator operation restricted)

 9 Engine runs on only one cylinder bank
- Mickdown downshift not possible
- warning lamp or CC message "Engine limp-home III Fault lamp is ON (check Engine or EML program"
- 99 None of the fault symptoms indicated is applicable.

E38 shown

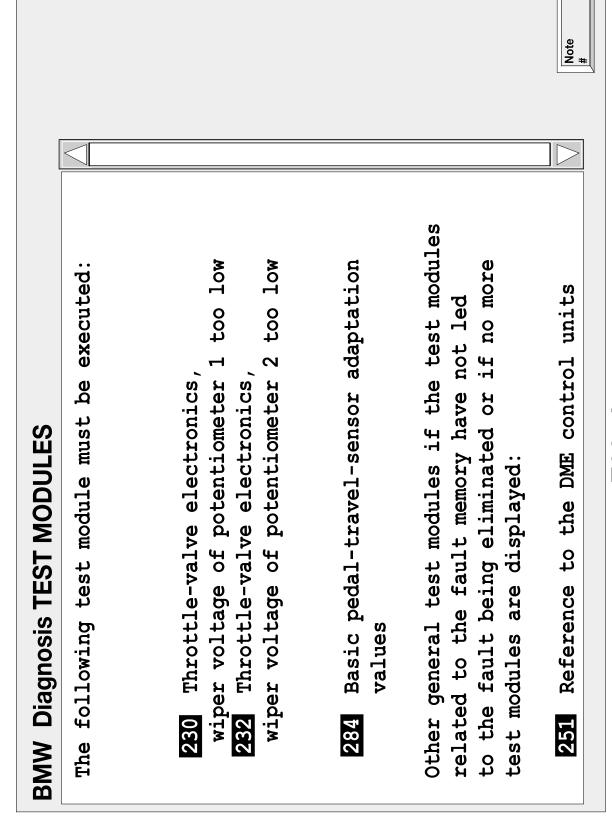
Note #

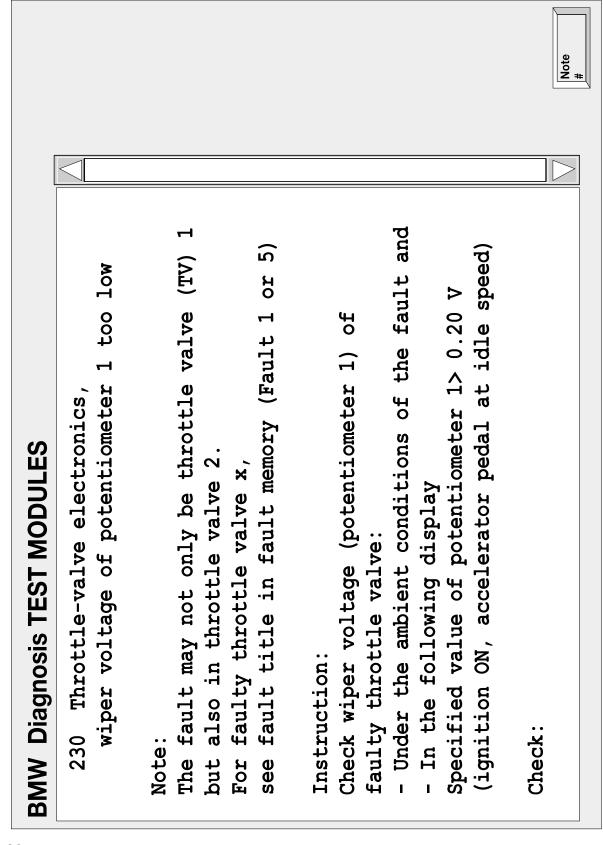


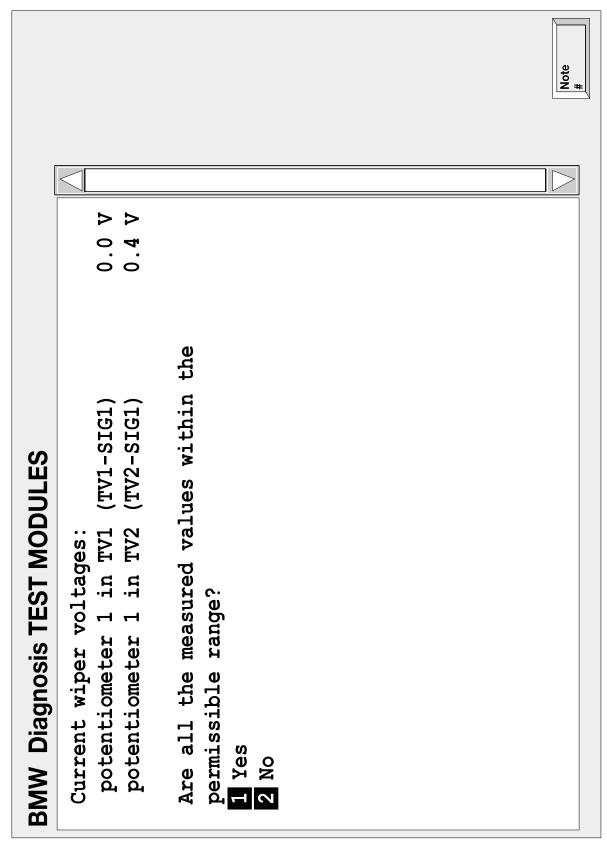
Do you want to continue troubleshooting?

Notes button: OBDII code (US only)

Note #







E38 shown

BMW Diagnosis TEST MODULES

230 Throttle-valve electronics, wiper voltage of potentiometer 1 too low

ote:

fault may not only be throttle valve (TV) also in throttle valve 2. but

For faulty throttle valve x,

fault title in fault memory (Fault 1 or 5).

see

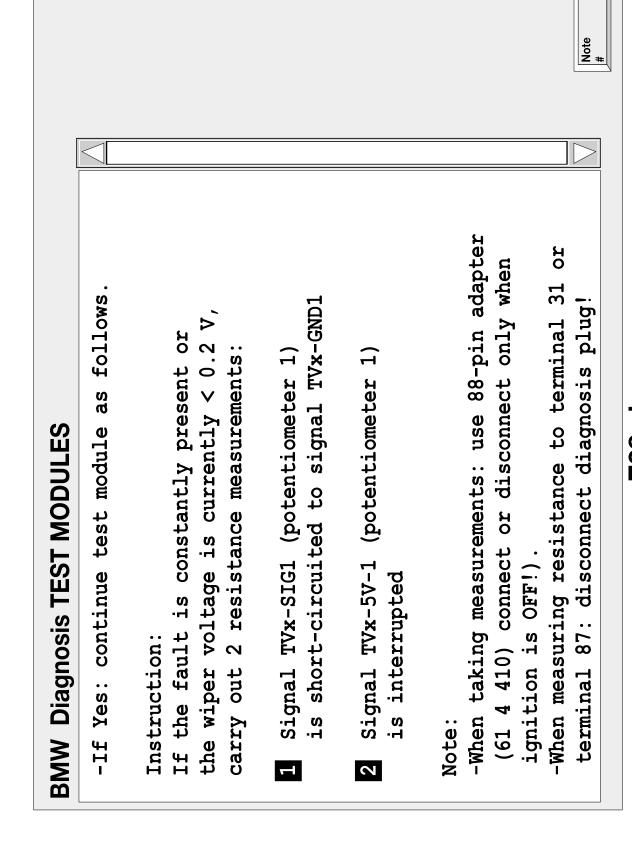
Check wires (only when ignition is OFF!) :

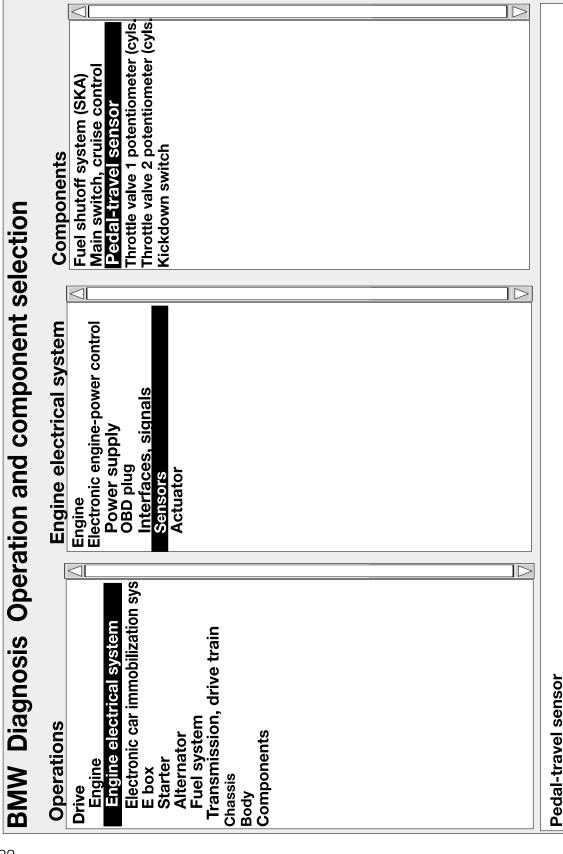
- Check all wires for visible damage.
- Check whether plug-in connections (controlcomponents) are fitted correctly and have unit connectors and connectors on the good contact.

Is the wire OK?

-If No: repair wire and/or plug-in connection and check whether fault is stored again.







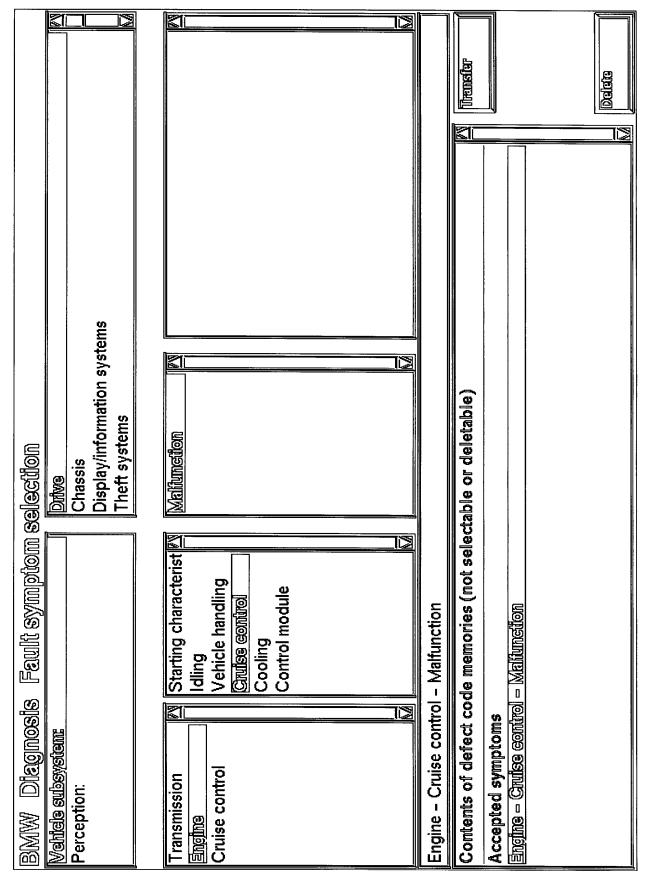
E46 shown

The EMLIIIS control unit assumes the start status for learn mode when the PWG necessary when replacing the EMLIIIS control unit or the pedal position sensor requirements. For this purpose, a measured signal (signal name PWGx-SIG; imes = In order to compensate for production-related tolerances in the pedal position The pedal position sensor in the EMLIIIS system is used to record the driver's 1, 2 or 3) proportional to the accelerator pedal angle is generated in a pair of - A new variant is coded in the EMLIIIS control unit; this is only possible with sensor (PWG) system, the PWG limit stop (idle point and kick-down limit stop) ensure this step is carried out, the engine will not accept the throttle system The valid value range of the accelerator pedal angle is between 0 and 99.6 to carry out PWG basic adaptation in order to adapt the new tolerances. To EMLIIIS control unit where they are processed in 3 evaluation circuits (sosensor failing that the driver's requirements are recorded without losses in 3 pedal position sensors are installed in order to ensure in the event of a The 3 measured signals are transferred via 3 shielded supply lines to the are determined in a basic adaptation-learn mode. For this reason, it is basic adaptation values are deleted by one of the following conditions: the encoding program "encoding ZCS" via the DIS or MoDiC testers. Segie adaptation of pedal position sensor Basic adaptation of pedal position sensor before PWG basic adaptation has been carried out. Pedal position sensor ((PWG)): FB Pedal position sensor (PWG) called angle pulse generator ICs, WIG-ICs). coils in the pedal position sensor (PWG). Diagnosis Document display Prottle position con-Pedal position sensor trol module (EML) A6004 Pedal position sensor SP W9110 W9110 Shield Shield ℥ ₹ 0.35 0.35 넁

	- Engine speed - Vehicle speed - Coolant temperature, engine - Coolant temperature, radiator outle - Oil temperature, engine - Intake-air temperature - Signal, driver's-wish sensor 1 - Signal, driver's-wish sensor 2 - Adaptation, driver's-wish sensor 2 - Adaptation, driver's-wish sensor 2 - Driver's-wish-sensor angle - Throttle angle - Signal 1, engine throttle - Adaptation 1, engine throttle - Signal 2, engine throttle	
ol unit functions Functions	Read fault memory Delete fault memory Component activation Dagnesis requesis	
BIMIW Diegnosis Control Gentral units	DIMIE Motor Electronies MS42	Messegges बाग्वी एक्डप्राफ्ति

BIMIW Diegnosis Control un	uniit functions			
Control units	Functions	Pa	Part functions	
ZKE Central body electronics	Identification		 Oil temperature, engine 	
DIME Motor Electronics MS42	Read fault memory	1	 Intake-air temperature 	
EGS Transmission control GS20	Delete fault memory		Signal, diliwer's—wish sensor 1	अन्तरी
x EWS Electronic immobilizer	Component activation		Adaptation, driver's—wish sensor '	Sensor 1
MFL Multi-function steering wheel	Diregmests requests		Signal, driver's—wish sensor 2	307 2
ASC stability control MK20			Adaptation, driver's—wish sensor 2	sensor 2
IHKA Heater/automatic A/C control			Ontver's-wigh-sensor angle	1
PDC Park Distance Control			Threfile angle	
RAD Radio			Signal 1, engine throttle	
KOM Instrument cluster		99	Adaptation 1, engine throttle	Me
x MRS Multiple Restraint System			Signal 2, engine throttle	
LSZ Lights switching center	-	9 9	– Adaptation 2. engine throttle	Me Me
		d -	Adaptation, coupling spring	ng G
		-	Voltage, air-mass flow sensor	nsor
		4 <u>-</u>	Air mass	
]_	Load signal	
Meseages and results				Display
Signal, driver's-wish sensor 1	0.72 V	Adaptation, driver's-wish sensor	-	
Signal, driver's-wish sensor 2	0.77 V	Adaptation, driver's-wish sensor 2	တ်	
Driver's-wish-sensor angle	o °P₩	Throttle-valve angle	å° 0 Xå° 0	<u> </u>
Signal 1, engine throttle	V 6.0	Adaptation 1, engine throttle	le 11.02 %	
Signal 2, engine throttle	0.9 V	Adaptation 2, engine throttle	le 10.83 %	
				77X

BIMIW Diagnosis Operation and component selection	등	and component selection			
				Gomponents	
Operations		,		Alrengely	
hicle		Misfire detection		AAA	
Drive		Injection		Solenoid valve, intake manifold (DIS,	
Voltage and current control		Cruise control		Idle actuator	
Starter control		Pedals		Air-mass flow sensor	
Electronics box, fan		Mixture induction	, '	Intake-air temperature	
Engine management MS42		A/C-compressor control			
Transmission control GS20		Knock control			
Chassis		Oxygen-sensor control			
Body		Mr supply			
Component and signal information		Engine-speed measurement			
Service functions		Engine cooling			
		Camshaft control			
		Suction jet pump			
		Interfaces			
		Secondary-air injection			
		Power supply			
		Control-unit test			
		Tank ventilation			
		Ignition			
		Symptoms			
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Engine throttle					
					71



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chedule	ion iding withed B1214 M0MFL		Ä
31MW Diagnosis Test schedule or test schedule	Engine - Cruise control - Malfunction - Imbarface, multil-function হহৈত্যামিল wheel ভাহাৰ MolAlfL) රූපුව පුණ්ඩල	? Engine throttle B1214_M0MDK
	ingin	Own.	_

